RADARSAT-2

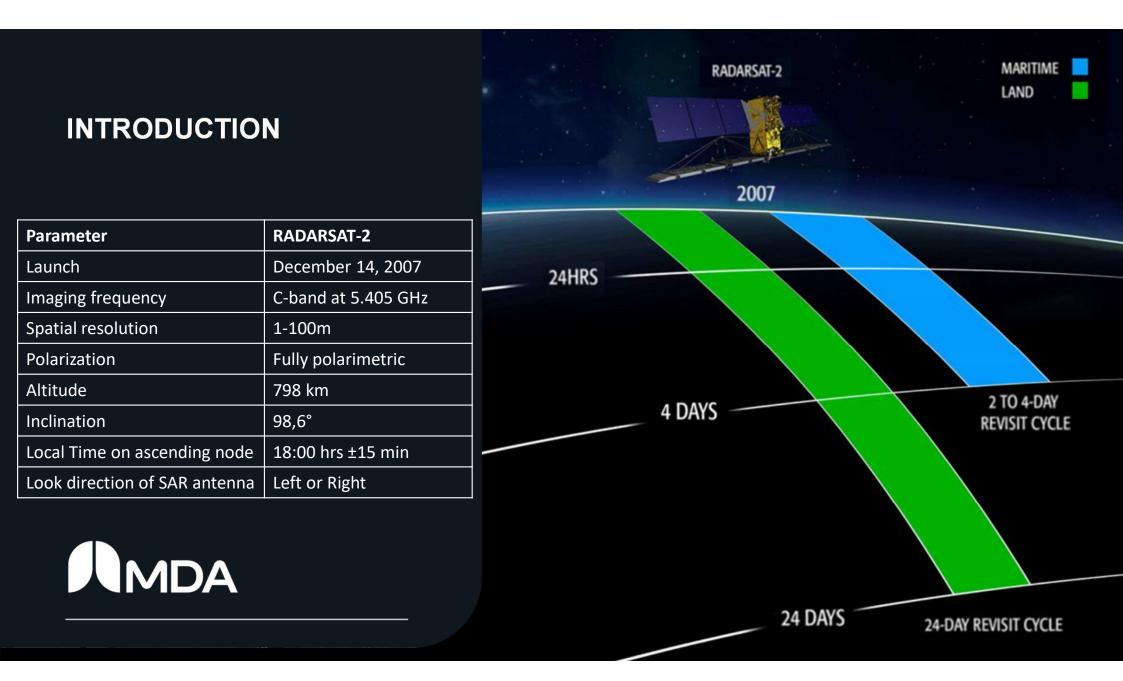
11/06/2021 presented by VIGISAT



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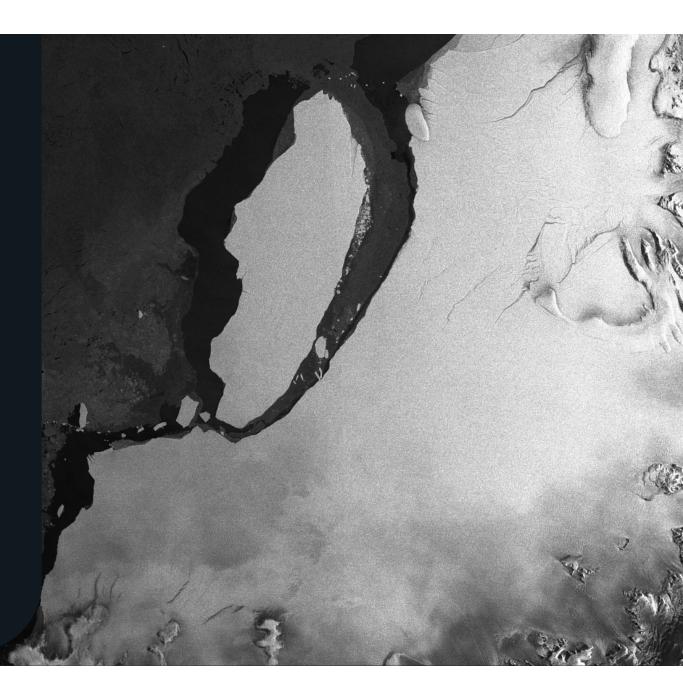


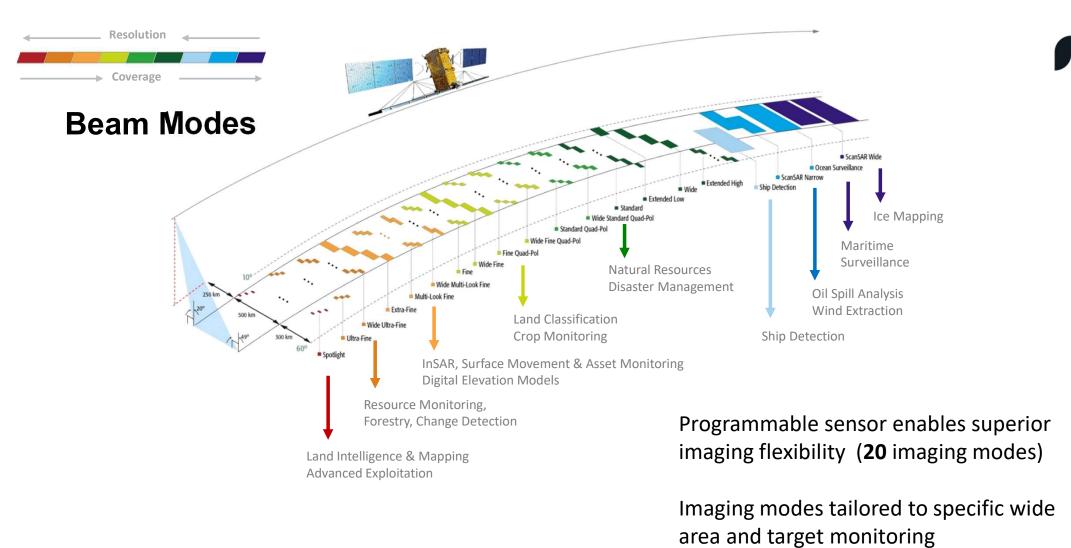
SECTION 2

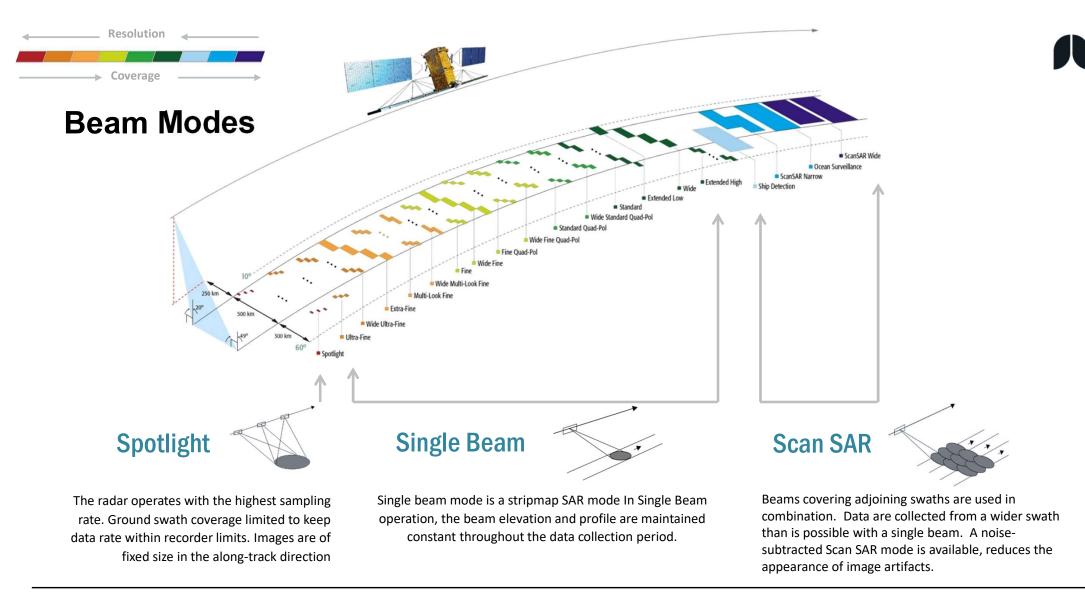
RADARSAT-2 Beam Modes



Imagery: Larsen Ice shelf calving, 2017 (SCWA)



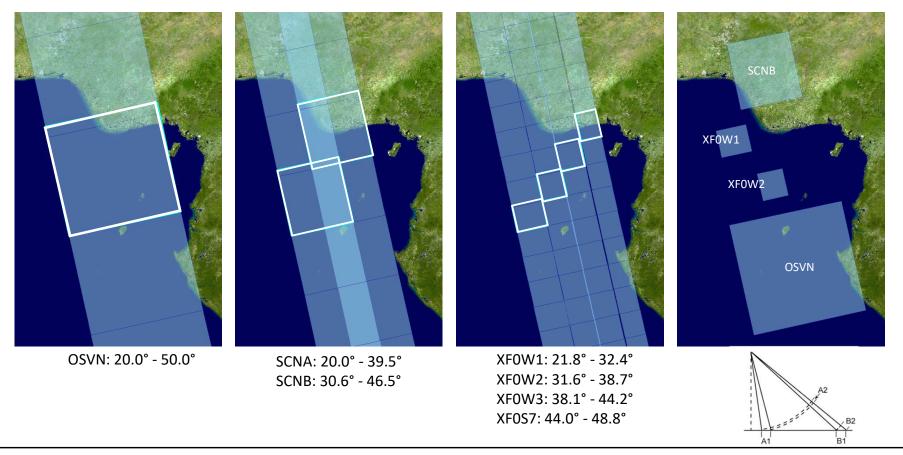




Section: Beam Modes

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Incidence Angle vs. Coverage



Section: Beam Modes

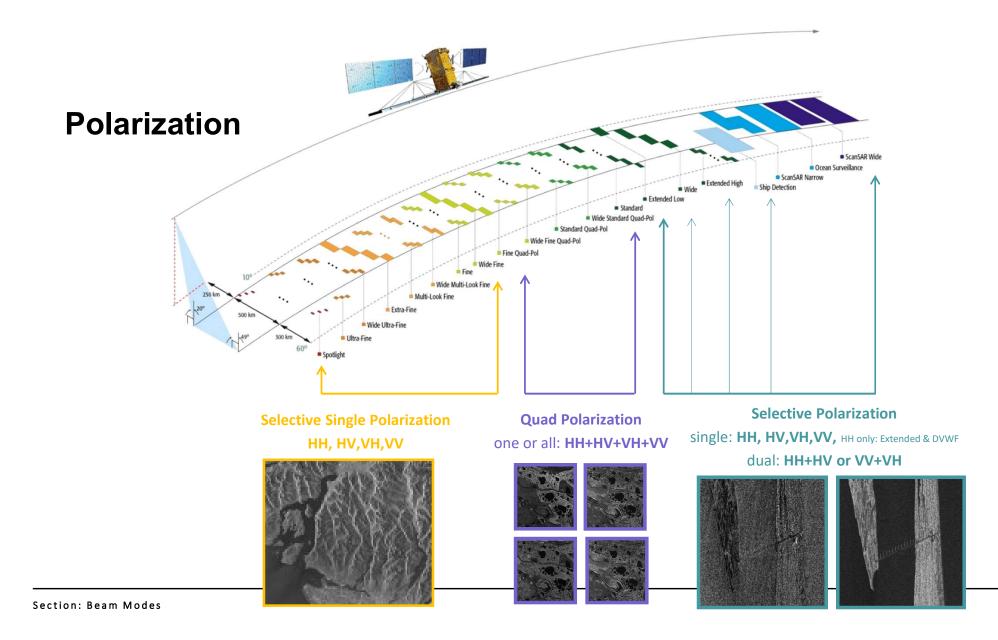
Beam Mode

Ship Detection (DVWF) **Ocean Surveillance (OSVN)** 500 x 500 ScanSAR Wide 500 x 500 ScanSAR Narrow Standard Wide Standard Quad Pol Standard Quad Pol Wide Fine Quad Pol Fine Quad Pol Wide Fine Fine Wide Multi-Look Fine Multi-Look Fine **Extra Fine** Wide Ultra-Fine **Ultra-Fine**

Scene Size

(km x km)

Resolution Coverage



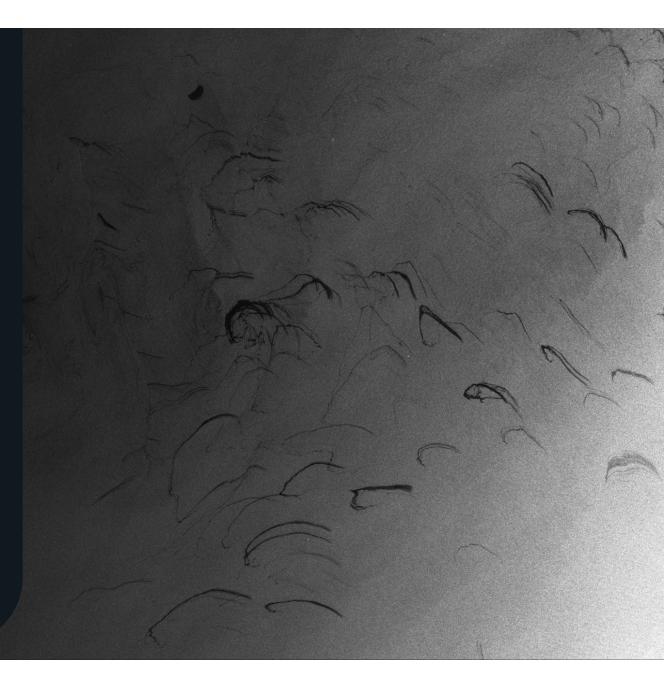
SECTION 2

Product Types

Product Types

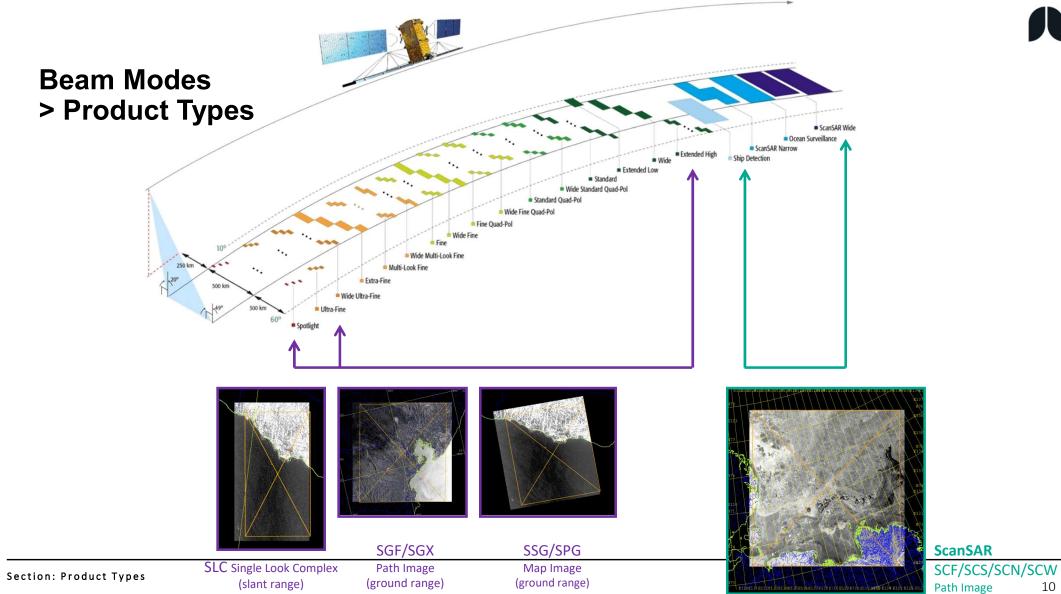
- Slant Range
- Ground Range
 - Path Image
 - Map Image

Calibration & Look Up Tables

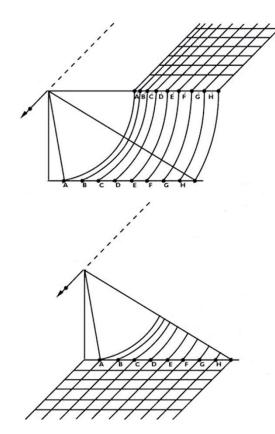




Imagery: Oil seeps in the Gul of Mexico (SCNA)



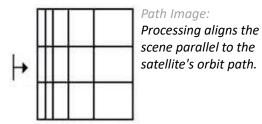
Product Types



Slant Range

range pixel spacing and range resolution are measured along a slant path perpendicular to the track of the sensor

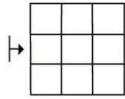
SLC; complex data, phase is maintained



Ground Range

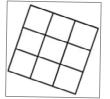
range pixel spacing and range resolution are measured in ground range coordinates, i.e. along an assumed Earth's surface that follows the shape of the ellipsoid at a local elevation height

SGF, SGX; magnitude detected pixels represented as unsigned integers





Processing aligns the scene parallel to the satellite's orbit path.



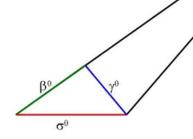
Map Image: Geocorrected to a map projection.

Calibration Type: Output Scaling LUT files

3 output scaling Look-up Tables (LUTs) are included with most products (all but SSG & SPG).

These LUTs allow you to convert the digital numbers found in the output product to sigma-nought, beta-nought, or gamma-nought values by applying a constant offset and range dependent gain to the SAR imagery.

This allows the user to directly scale the integer pixel values back to beta0, sigma0 and gamma0 backscatter.



Beta nought is the radar brightness coefficient

Sigma nought is the measure of the strength of radar signals backscattered Gamma nought is typically used when calibrating the antenna.

🅌 schemas	
🗟 Browselmage.tif	
🚾 imagery_HH.tif	
💼 imagery_HV.tif	
🔮 lutBeta.xml	
📄 lutGamma.xml	
🔮 lutSigma.xml	
📄 product.xml	
Readme.txt	
🔁 User_License.pdf	

SECTION 2

Product Selection

Acquisition Planning

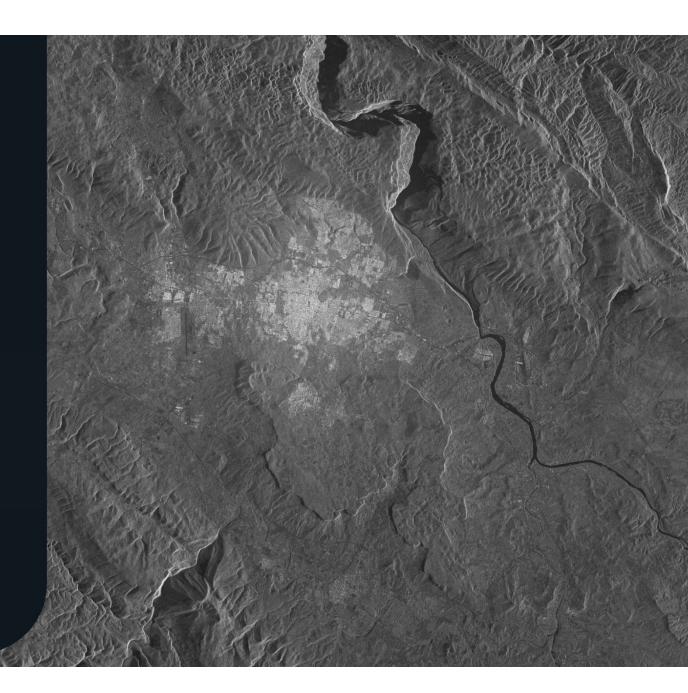
- Beam mode
- Product Type
- ✓ Format

Tasking & Ordering

- Programming Level
- Delivery Priority



Chiapas, Mexico (U10W2)



Product selection

Acquisition Planning

Beam Mode

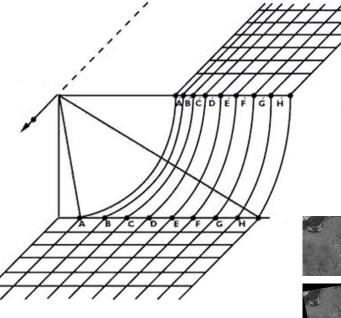
- ✓ Coverage vs. Resolution
- ✓ Incidence Angle
- ✓ Polarization

Product Type

- 1. Slant Range
- 2. Ground Range
 - a) Path Image
 - b) Map Image

Format

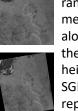
- 1. RS2 GTIFF + XML
- 2. Value Added



Slant Range

range pixel spacing and range resolution are measured along a slant path perpendicular to the track of the sensor SLC; complex data, phase is maintained

Ground Range



range pixel spacing and range resolution are measured in ground range coordinates, i.e. along an assumed Earth's surface that follows the shape of the ellipsoid at a local elevation height

SGF, SGX; magnitude detected pixels represented as unsigned integers

Section: Product Selection

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Product selection

Tasking & Ordering

Programming Level	Order Submission (before tasking)	Priority	
1. Emergency Programming	4 - 12 hours	Highest	
2. Guaranteed Time Critical (GTC)	> 72 hours	Precedence over NTC, TC	
3. Time Critical (TC)	> 72 hours	Precedence over NTC	
4. Non Time Critical (NTC)	> 72 hours	Standard, precedence over Late	
5. Late Programming	12 - 72 hours	Lowest	
Delivery Priority	Latency from reception to delivery		
1. Near-Real Time	< 4 hours	Best effort, within 1 hour of downlink	
2. RUSH	< 24 hours	~6 – 24 hours	
3. Regular	< 5 days	~26 hours	

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Questions?



